



L'enjeu des machines accélérées



Future evolutions : top 500 supercomputing list nov. 2021





Top 500 list : the 10 fasten supercomputer Past decade Nov. 2021

#1 (Nov 2021) : Fugaku (Japan) : 7,5 M cores ARMFX64, ~ 0,5 ExaFlops

Color code :

- Accelerator (GPU)
- Any cores
- General purpose processor
- General tendency is on accelerator based system (GPU computing)
- Or Many Cores systems (1M+ cores)
- Convergence of HPC, AI & HPDA

ank	System	Cores	
	Supercomputer Fugaku - Supercomputer Fugaku, A64FX 48C 2.2GHz, Tofu interconnect D, Fujitsu RIKEN Center for Computational Science Japan	7,630,848	
	Summit - IBM Power System AC922, IBM POWER9 22C 3.076Hz, NVIDIA Volta GV100, Dual-rail Mellanox EDR Infiniband, IBM D0E/SC/Oak Ridge National Laboratory United States	2,414,592	
	Sierra - IBM Power System AC922, IBM POWER9 22C 3.1GHz, NVIDIA Volta GV100, Dual-rail Mellanox EDR Infiniband, IBM / NVIDIA / Mellanox D0E/NNSA/LLNL United States	1,572,480	
	Sunway TaihuLight - Sunway MPP, Sunway SW26010 260C 1.45GHz, Sunway, NRCPC National Supercomputing Center in Wuxi China	10,649,600	*)
	Perlmutter - HPE Cray EX235n, AMD EPYC 7763 64C 2.456Hz, NVIDIA A100 SXM4 40 GB, Slingshot-10, HPE D0E/SC/LBNL/NERSC United States	761,856	
	Selene - NVIDIA DGX A100, AMD EPYC 7742 64C 2.256Hz, NVIDIA A100, Mellanox HDR Infiniband, Nvidia NVIDIA Corporation United States	555,520	
	Tianhe-2A - TH-IVB-FEP Cluster, Intel Xeon E5-2692v2 12C 2.26Hz, TH Express-2, Matrix-2000, NUDT National Super Computer Center in Guangzhou China	4,981,760	*
	JUWELS Booster Module - Bull Sequana XH2000, AMD EPYC 7402 24C 2.8GHz, NVIDIA A100, Mellanox HDR InfiniBand/ParTec ParaStation ClusterSuite, Atos Forschungszentrum Juelich (FZJ) Germany	449,280	-
	HPC5 - PowerEdge C4140, Xeon Gold 6252 24C 2.1GHz, NVIDIA Tesla V100, Mellanox HDR Infiniband, DELL EMC Eni S.p.A. Italy	669,760	
0	Voyager-EUS2 - ND96amsr_A100_v4, AMD EPYC 7V12 48C 2.45GHz, NVIDIA A100 80GB, Mellanox HDR Infiniband, Microsoft Azure Azure East US 2	253,440	

Journée CLIMERI France - L'enjeu des machines accélérées



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France (GENCI & meteo-france) is following the general tendency

- IDRIS : Jean-Zay : ~ 2696 GPU Nvidia V100 (5/6 of JZ peak performance), 28PF
- CINES : Adastra (2022) : AMD manycore (Genoa) + GPU (MI200), 70PF
- CEA/TGCC : AMD Rome, 128 cores by nodes, 300 000 cores, similar to many core system
- CEA/TGCC : 256 GPU NVIDIA V100
- **•** CEA/TGCC : 80 Nodes Arm Fujitsu A64FX (48 cores by socket, FUGAKU-like)
- Meteo-France : Belenos/Taranis : AMD EPYC ~300 000 cores
- But, for now, keep a large part of general purpose processors...

Next Step : French Exascale computer -> 2024 + ?

- EuroHPC call for exascale supercomputer (50% funded by Europe) : ~2023-2024
 - 2 hosting site candidates : TGCC (France) & FJZ (Germany)
- Should use European technology
 - $\,\circ\,$ ARM Zeus core + Titan Risc-V accelerator + BXI interconnect
- Due to delay on the roadmap and to fulfil the expected targets (performance , consumption)
 => would be probably mostly composed of GPU accelerators : Nvidia, AMD or Intel
- Announced part of general purpose processors : 20 40 % : Price or peak performance ?
 - $\,\circ\,$ 20 % of price => ~ 5% of peak performance
- **"Exascale France " project : prepare the applications to exascale**

=> Not a clear idea of what would be the hardware architecture and technology for the future Exascale French machine









Goal : reach the European technological independence on computing processors



- **Common platform based on ARM64 (general purpose) and Risc-V for accelerator + BXI interconnect (ATOS)**
- **Growing interest for ARM of many country to achieve strategic path to exascale**
 - $\,\circ\,$ Japan (RIKEN), India (MEYTI-CDAC), South Korea (ETRI K-AB21), Europe...

Accelerator hardware strategy seems not to be so well defined, and will not be ready for first exascale European computer



GPU : how does it works ?

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- Thousands of small core (3456 for Nvidia A100)
 - \circ 9,7 TFs, 2TB/s memory bandwidth (HBM2)
- 3 internal levels of parallelism
 - $\circ~$ Coarse grain (gang / teams)
 - \circ Fine grain (worker)
 - \circ Vectorisation (vector)
- # #Threads = #gang * #worker *# vector ==> O(10000 threads) to ensure performance
- SIMT paradigm : Single Instruction Multiple Threads
- Performance comes from quick switching between threads context to overlap memory access latency
- Each computing kernels (loops) are offloaded from the host (CPU) to the device (GPU)





Computation on GPU is "free lunch", performance bottlenecks come mainly from memory access and data transfer between host and GPU



- **By the past, specific low level language (CUDA) or API (OpenCL)**
 - $\,\circ\,$ Very intrusive for models, difficult to port large part codes
- Now recommendation is to use high level approach based on directives ; 2 main standards :
 - $\circ~$ OpenACC : most complete standard driven mainly by NVIDIA
 - OpenMP 4.5 / 5 : specific directives have been added to the standard for accelerator, late on OpenACC, but would more largely supported by other GPU vendors (AMD, Intel)
- Other high level approach
 - $\,\circ\,$ Language : kokkos, Raja... => not standard, need to rewrite
 - $\,\circ\,$ Domain Specific Language : STELLA, PSYCLON, home made...
- Each loops (kernels) must be instrumented to be offloaded on the GPU
 - Directives to manage loop parallelism (!\$ACC parallel loop, \$ACC kernels)
 - $\,\circ\,\,$ Directives to manage data transfer and allocation on GPU (data clause)

```
      I$ACC kernels
      I$ACC

      do i=1, n
      do i=

      do j=1, n
      a(i)

      enddo
      !$ACC

      do j=1, n
      !$ACC

      do j=1, n
      !$ACC

      enddo
      !$ACC

      isenddo
      !$ACC
```

```
!$ACC parallel copyout(a(:1000))
!$ACC loop
do i=1, 1000
a(i) = i
enddo
!$ACC end parallel
!$ACC data copy(a(:1000))
do 1=1.100
    !$ACC parallel
    ISACC loop
    do i=1, 1000
     a(i) = a(i) + 1
    enddo
    !$ACC end parallel
enddo
!$ACC end data
```

```
!$acc parallel
!$acc loop worker vector
do i=1,nx
    A(i)=1.0_8
end do
!$acc loop worker vector reduction(+:somme)
do i=nx,1,-1
    somme=somme+A(i)
end do
!$acc end parallel
```



DYNAMICO CPU Vs GPU



"Contrat de progrès" IDRIS+GENCI+HPE+LSCE 3 peoples for 3 months OpenACC

Only atmospheric dynamic No I/O

Low resolution 1 GPU (V100) ~= 4.5 Intel CC ~= 90 cores

High resolution 1 GPU (V100) ~= 6 Intel CC ~= 120 cores





- **Port of simple atmospheric physics with 21 parameters on GPU**
 - Idris Hackathon May 2021 (T. Dubos &al.)
 - \circ OpenACC
 - $\,\circ\,$ ~2000 code lines, dynamics with DYNAMICO
 - $\circ\,\,$ ~1 week work

llm	ngrid (per GPU)	nbp	dt (dyn)	itau_phys	run_length	steps (phys)	CPU total	GPU total	speedup
79	4000	40	480	5	864000	360	5 <i>,</i> 633	0,971	5,80
79	16000	80	240	5	432000	360	24,841	2,841	8,74
79	64000	160	120	5	60000	100	31,483	2,652	11,87
79	256000	320	60	5	30000	100	170,93	10,054	17,00

Speedup : 1 GPU nodes Vs 1 CPU Nodes == 4 gpu V100 Vs 2 intel Cascace Lake

- $\,\circ\,$ Low resolution (200km) : 1 GPU ~ 58 cores CCL
- $\,\circ\,$ High Resolution (25km) : 1 GPU ~ 170 core CCL

Greatest benefits for high resolution run

- Low resolution runs exhibit interesting benefit only inside 1 GPU node
- Potentially and probably no decreasing of elapsed time compared to massively parallel CPU computing





Full ESM : 500 000 ~ 600 000 code lines

- Each component ~ 50 000 Loc -> 250 000 Loc
- Not every thing would be accelerate
 - $\,\circ\,$ Communications, I/O, III-formed code part, lake of man-power, late or new component
- What would not be accelerated will be run by the host but on less CPU resources
 - $\circ~$ Generally 1 MPI process drive 1 GPU
 - $\,\circ\,\,$ Difficult to manage both openMP and GPU kernel within OpenACC (maybe better using only openMP5 only)
 - $\,\circ\,$ So 4 cores will be used to drive 4 GPU over the 40 cpu cores available (CC, IDRIS)
 - R, ratio between GPU and equivalent cpu core to reach the same SYD (or elapsed time) for the accelerated part : ex: Dynamico R ~ 100 cores/1GPU
 - $\,\circ\,$ So the part that would not be accelerated will run R times slowly
 - $\,\circ\,$ In this specific case, more than 99% of the computing work must be running on the GPU to shows some benefit

What is important is not what had been ported onto GPU, but what has not been ported onto GPU

- $\,\circ\,$ More easy for model with small part of code that consume 99.9% of computing time
- $\circ~$ But climate models have a relatively flat profile...
- Solution will consist to share computing work both on CPU and GPU
 - $\circ~$ Default behaviour is CPU are idle when GPUs compute kernels
 - \circ openMP + GPU
 - $\circ~$ Distribute work across idle CPU cores and GPU

But it will considerately increase the degrees of complexity of the model

!! Importance of the code redesign !!



The supercomputing landscape is changing in depth, introducing new paradigms...

- Convergence of ML, AI <-> HPC
- Massive integration of GPU-based accelerators (more than 90% of the peak perf.)
- No other more friendly alternative at short term.

GPU computing is working very well for many scientific thematic and for IA

But future accelerator or many cores systems will probably not improved significantly time to solution for climate modeling (IPSL) but will make possible large ensembles and/or high resolution runs.

Major difficulties come from the volume of models, their heterogeneity and complexity.

Major code redesign & rewriting will be needed to achieve good performance on GPU.

- How to make an efficient port without falling to "Ninja Programming" ?
- How to maintain porting for non-expert researcher without freezing new developments ?

Emulate physical processes with AI can be a way to port efficiently part of models onto GPU

- This way merit to be explored (TRACCS)
- But not (yet) proved to be working efficiently for climate modeling

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