

# Are GCMs obsolete?

Climeri Webinar

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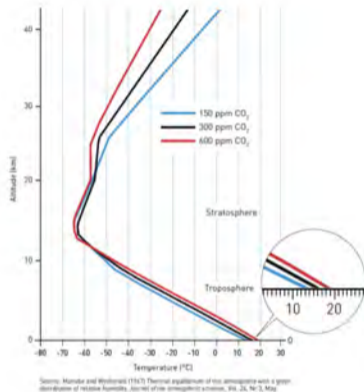
# Outline

- 1 The structure of the GCM, from Manabe to present-day
- 2 Computing technology: bigger, not faster
- 3 Emulators: climbing down the ladder
- 4 Are GCMs obsolete?

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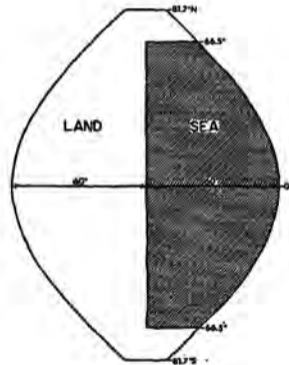
# Manabe and Wetherald (1967): 1D model response to CO<sub>2</sub> doubling



“Radiative convective equilibrium of the atmosphere with a given distribution of relative humidity is computed as **the asymptotic state of an initial value problem**.”. Syukuro Manabe won the Nobel Prize in Physics, 2021.

# Manabe and Bryan (1969)

- Recognized as a “milestone in scientific computing”, Nature (2006).
- Sector model of  $120^\circ$
- 1 atmospheric year coupled to 100 ocean years
- 1200h for 1 simulated year (0.02 SYPD) on Univac 1108



# Atmospheric response to doubled CO<sub>2</sub>

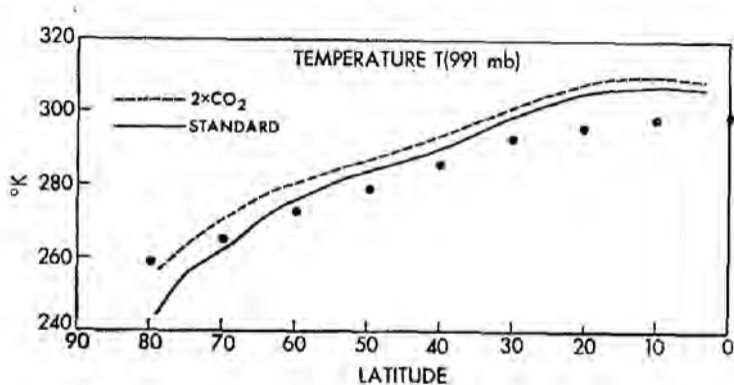


Fig 5 from Manabe and Wetherald (1975), equilibrium response to doubled CO<sub>2</sub>.

# Atmospheric response to doubled CO<sub>2</sub>

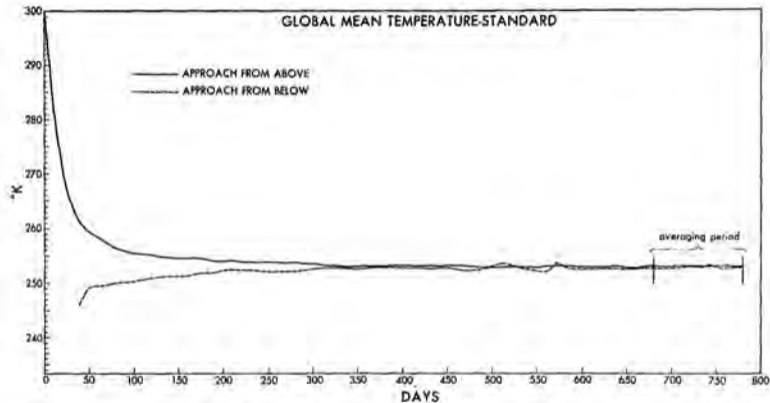
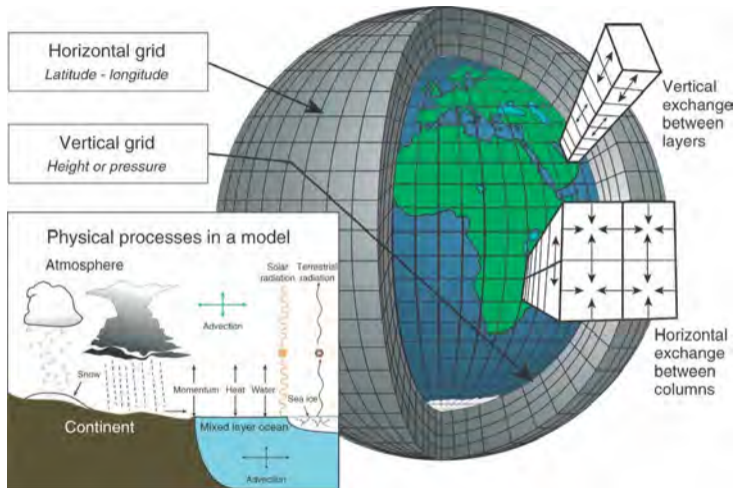


Fig 3 from Manabe and Wetherald (1975), equilibrium response to doubled CO<sub>2</sub>. Spinup times in modern GCMs can be  $\mathcal{O}(1000)$  years.

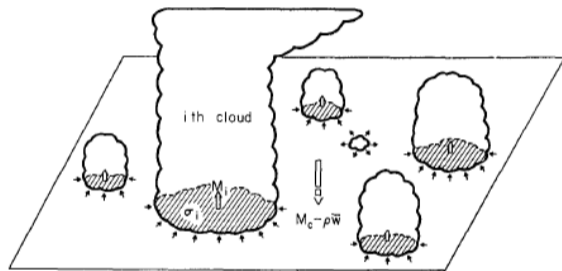
# The structure of a GCM, from Manabe to present day



From [Edwards \(2011\)](#).  $\mathcal{O}(10X)$  increase in resolution from Manabe and Bryan to CMIP6.



# Parameterizing convection: slow(?) progress over 50 years



Arakawa and Schubert (1974): *Interaction of a cumulus cloud ensemble with the large-scale environment.*

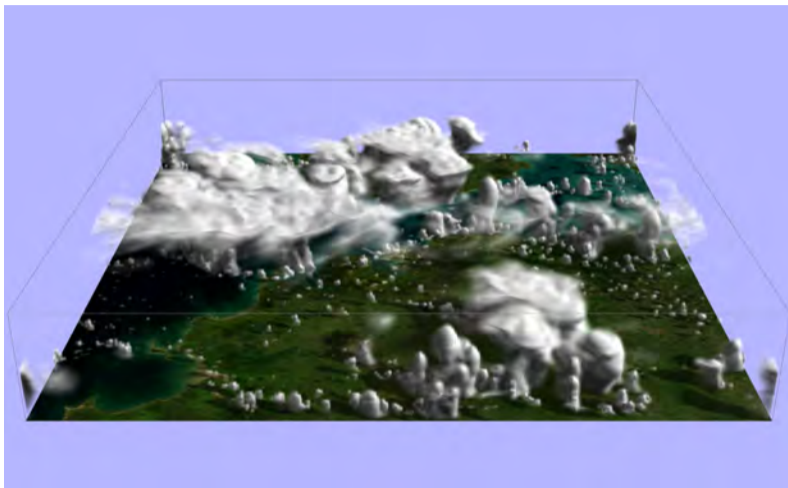
# Is the column broken?

Can the redistribution of heat, moisture, momentum by clouds be written as a function of a column state? In other words, **are clouds parameterizable at all?** The answer has often been **no**. “A problem that refuses to die”. **Randall (2003)**

- Too many cloud habits
- Organized deep convection: squall lines, tropical cyclones, mesoscale convective systems: **non-local** physics from a column perspective.
- Sensitivity to small-scale dynamics: entraining updrafts, cold pools.
- Sensitivity to details of microphysics.
- Schemes tend to begin simple and end Ptolemaic.
- Systematic biases across GCMs.

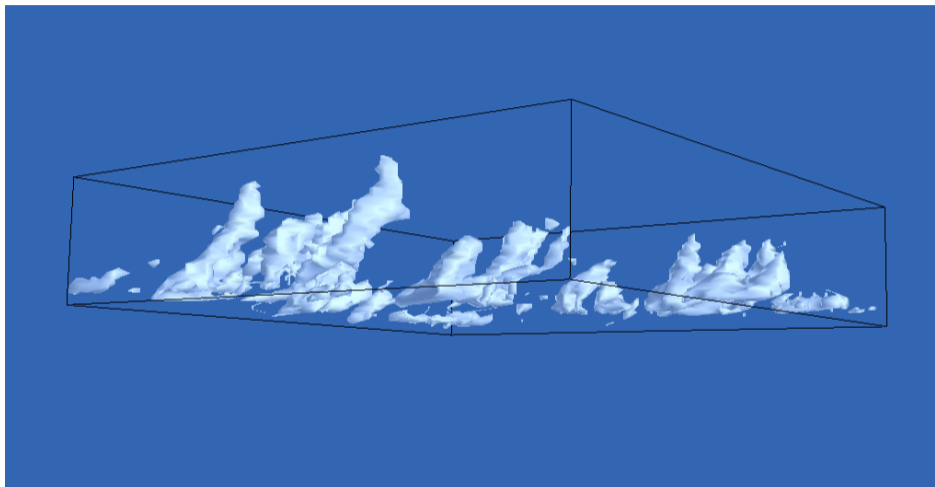


# Resolving atmospheric deep convection: CRMs



Courtesy W.-K. Tao, NASA. We can begin to resolve deep convection at km-scale.

# Resolving boundary layer clouds: LES models

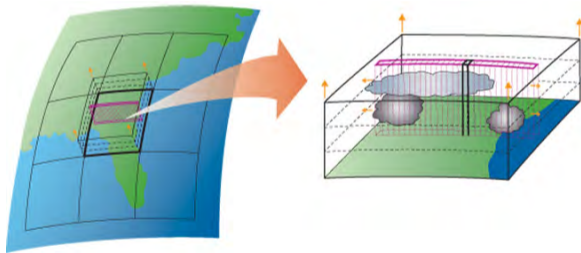


Courtesy UKMO [GASS project](#). Typical resolution,  $\mathcal{O}(10\text{ m})$ .

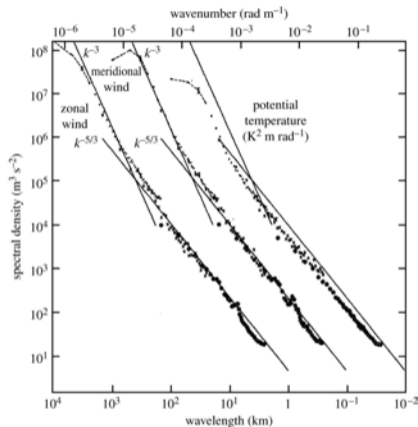
# Superparameterization: embedded CRMs

From [Randall \(2003\)](#). [Parishani et al \(2017\)](#) attempt the same for boundary layer clouds.

- Assumes **scale separation** between GCM gridscale and embedded model.
- Only 2D CRMs feasible for computational reasons (or 2 orthogonal ones).
- CRMs can retain memory of their state, and potentially communicate with neighboring CRMs to enable mesoscale organization.
- Some success in improving climate simulations, but too expensive for a workhorse.
- Early target for ML: [Gentine et al \(2018\)](#)

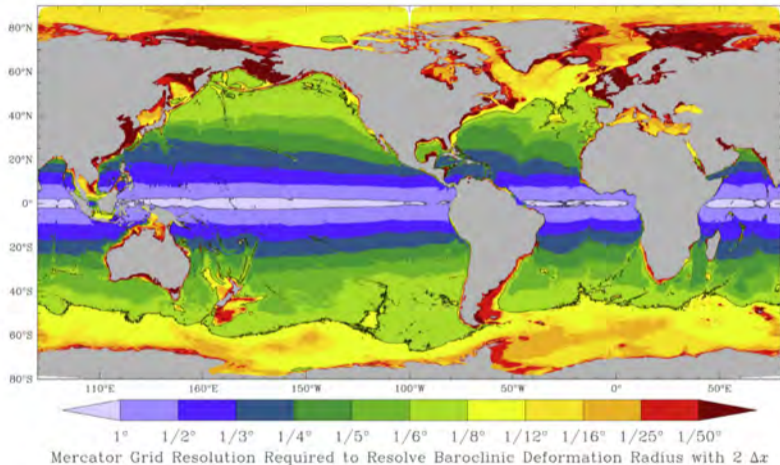


# No separation of "large" and "small" scales



Nastrom and Gage (1985). More model fidelity, more complexity over time in small scales (“physics”). The **backscatter** idea (Jansen and Held 2014) provides an energetically consistent framework for SGS.

# Eddy resolving scales in the ocean



From [Hallberg \(2013\)](#).

# Coarse-graining without scale separation



eNATL60 dataset courtesy Julien le Sommer and collaborators. Can we assume a structure for learning. e.g “GM+E” [Bachman 2019](#)? See Sommer et al AGU 2019.



# The climate Turing test: global CRMs

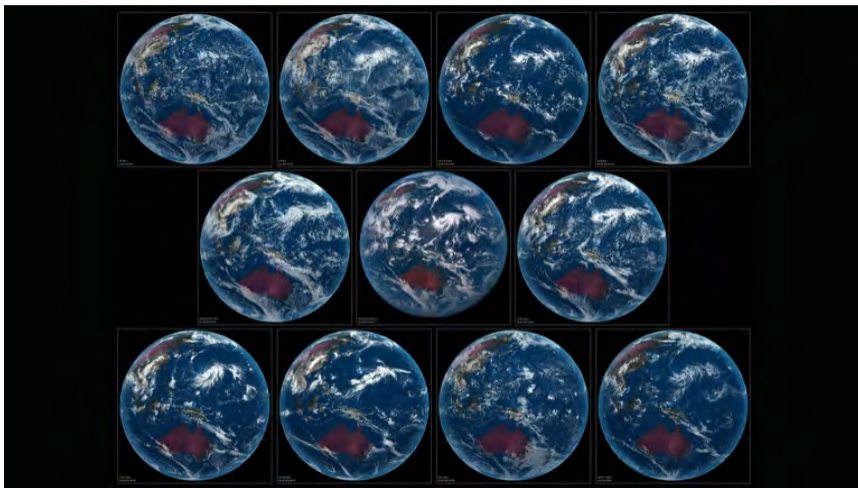
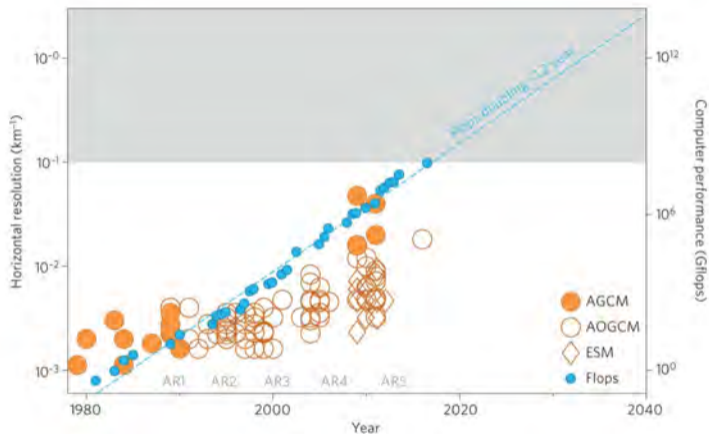


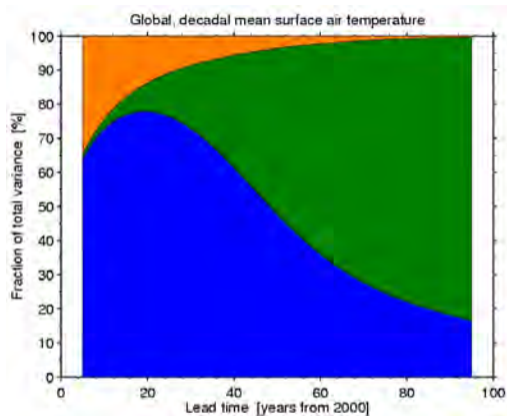
Figure courtesy the [DYAMOND](#) initiative.

# Evolution of model resolution



From [Schneider et al \(2017\)](#). At GFDL: 10X from Manabe and Bryan (1969) to Held et al (2019).

# Science requires going beyond observations

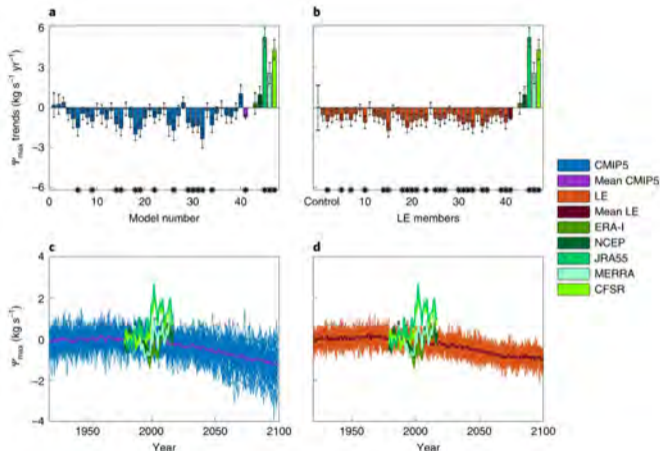


Sources of uncertainty in climate simulation:

- *chaotic uncertainty* or internal variability
- *scenario uncertainty* dependent on policy and human actions.
- *structural/epistemic uncertainty* or imperfect understanding.

Models must also generate **counterfactual** values! From [Hawkins and Sutton \(2009\)](#).  
Baseline requirement: a climate model must be capable of **100 simulations of 100 SY each in 100 days**.

# Overfitting to present day climate?

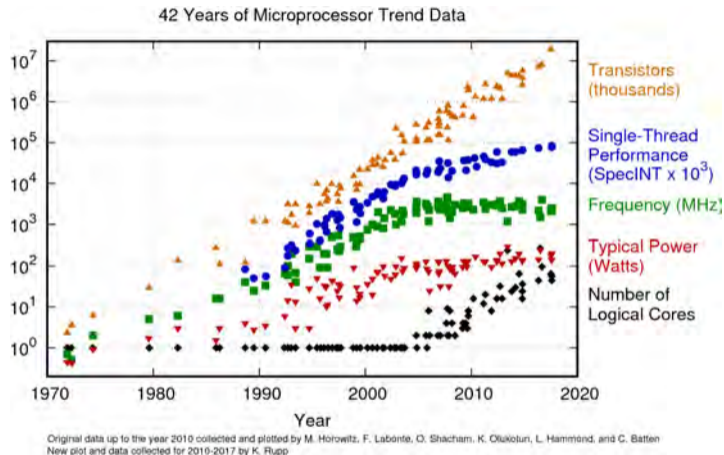


Hadley cell strength is likely correct in models and not in “observations”!  
From [Chemke and Polvani \(2019\)](#).

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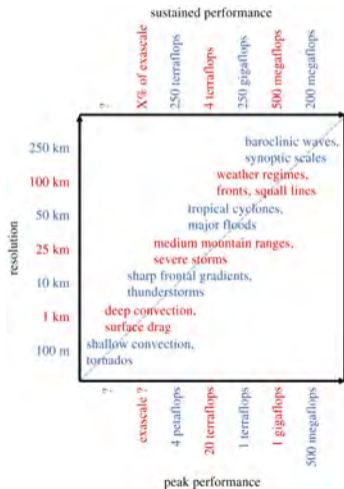
# End of Dennard scaling: computers get bigger, not faster



From [42 Years of Microprocessor Trend Data](#), courtesy Karl Rupp. **Weak scaling** (bigger problems in the same time) works, **strong scaling** (same problem in less time) doesn't.

# What can we expect at an exaflop?

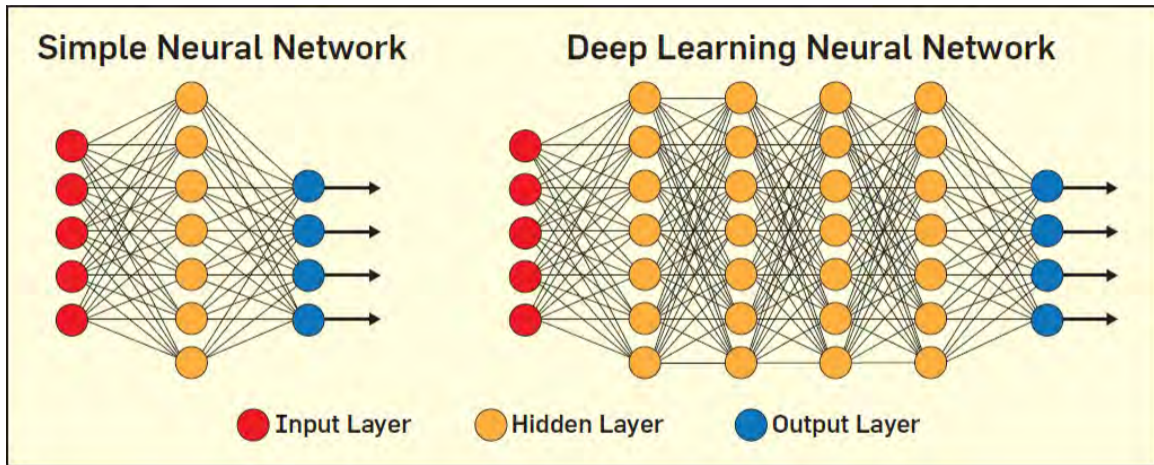
Will exascale be the rescue? [Neumann et al \(2019\)](#).



Hypothesis: vastly reduced uncertainty at  $\sim 1$  km (see “digital twins”, DestinE, NextGEMS, ...)

- ICON projects that a 1 km global model will run at **0.06 SYPD** on “pre-exascale” technology: **17X** improvement needed for 1 SYPD.
- Large nodecount, see e.g [Caldwell et al \(2021\)](#).
- DECK: **1000 SY**.
- A full suite of hindcasts for seasonal forecasting: **10,000 SY**.
- Ocean state needed for seasonal prediction and beyond as well!

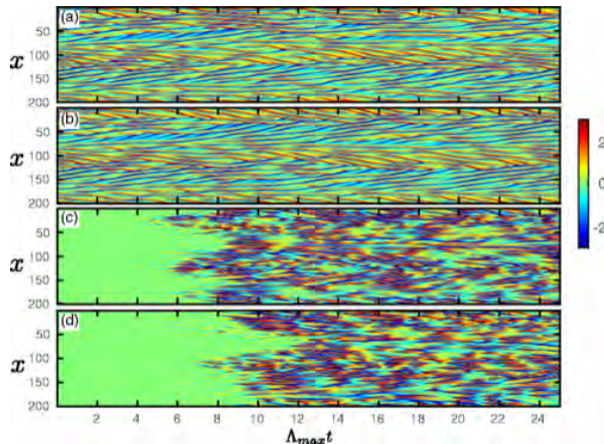
# Deep Learning



From [Edwards \(2018\)](#), ACM. **Dense linear algebra** with high operation intensity, data-intensive.

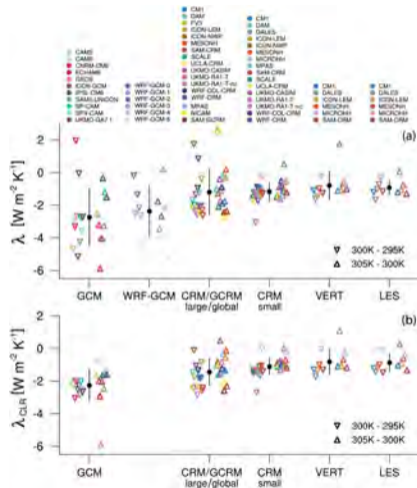


# Model-free prediction for stationary problems



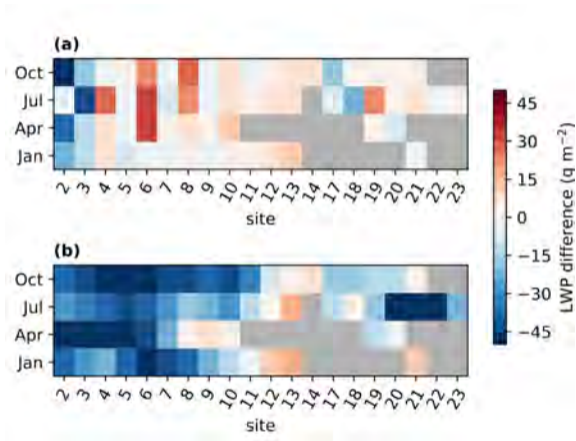
From [Pathak et al, PRL \(2018\)](#), *Model-Free Prediction of Chaotic Systems from Data*. See also [Patel et al \(2021\)](#). But **climate is non-stationary**, see [O’Gorman and Dwyer \(2018\)](#), [Dixon et al \(2016\)](#). Use models “up the ladder” for training.

# Extreme spread in climate sensitivity in RCEMIP



From [Becker and Wing \(2020\)](#).

# LES reduces GCM structural uncertainty, but has its own



From [Shen et al 2021](#). Sensitive to LES details (numerics, closure), see [Couvreur et al \(2020\)](#), [Beare et al \(2006\)](#), [Siebesma et al \(2006\)](#), ...

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# ML for model calibration: the sales pitch!

- Models, even “seamless” ones, may be configured or calibrated differently for different problems (e.g forecast horizons).
- Each problem carries an implicit **cost function** by which a model configuration is declared suitable.
- Models do not converge cleanly with resolution: much unresolved physics is not yet “scale-aware”.
- Computation alone is not going to make the problem go away (not everyone agrees...)
- Important new constraints on models from observations (new generation of satellites, Argo...)
- While **data science** is a misnomer (what is non-data science?) the **convergence of computation and statistics** that we call ML provides paths forward toward seamlessness: **traceable hierarchies of scale**, *Charney's ladder*

# Model calibration

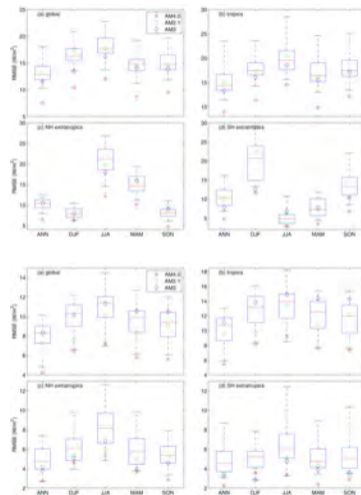
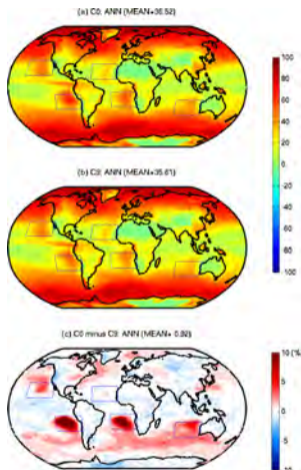
Model calibration or “tuning” consists of reducing overall model error (relative to some goal of modeling) by modifying parameters. In principle, minimizing some cost function:

$$C(p_1, p_2, \dots) = \sum_1^N \omega_i \|\phi_i - \phi_i^{obs}\|$$

- Usually the  $p$  must be chosen within some observed or theoretical range  
 $p_{min} \leq p \leq p_{max}$ .
- “Fudge factors” (applying known wrong values) generally frowned upon (see [Shackley et al 1999](#) on “flux adjustments”).
- The choice of  $\omega_i$  is part of the lab’s “culture”. Cost also plays a role.
- The choice of  $\phi_i^{obs}$  is also troublesome:
  - overlap between “tuning” metrics and “evaluation” metrics.
  - “Over-tuning”: remember “reality” is but one ensemble member...

See for example, [Hourdin et al \(BAMS 2017\)](#)

# Example: the tuning of GFDL's AM4/OM4/CM4 models



From [Zhao et al \(2018\)](#).

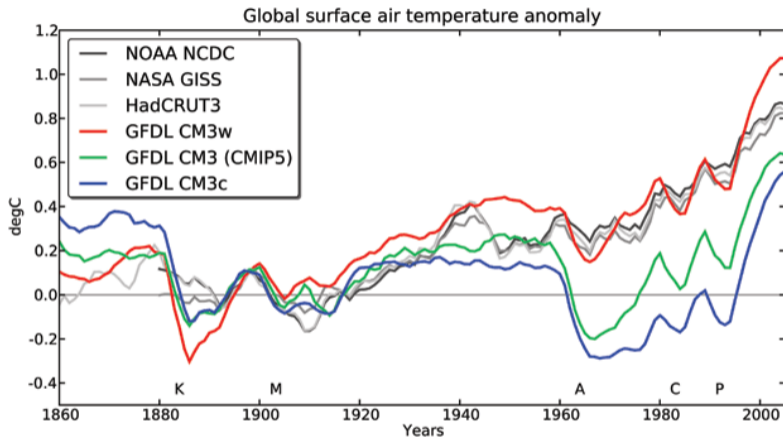
## Example: the tuning of GFDL's AM4/OM4/CM4 models

- The GFDL Global Atmosphere and Land Model AM4.0/LM4.0: 2. Model Description, Sensitivity Studies, and Tuning Strategies
- The GFDL Global Ocean and Sea Ice Model OM4.0: Model Description and Simulation Features: “We hypothesize that the development of a climate model is optimized only with close coordination across component model development.”
- Structure and Performance of GFDL's CM4.0 Climate Model: “CM4.0 is sensitive to a number of features [...] much less apparent in uncoupled atmosphere/land simulations”
- Climate Sensitivity of GFDL's CM4.0
- The GFDL Earth System Model Version 4.1 (GFDL-ESM 4.1): Overall Coupled Model Description and Simulation Characteristics

The JAMES special issue on GFDL's “4 series” models. 50,000 SY of coupled models run during model development, 10,000 SY of “CMIP6 runs”.



# Should we tune to get the 20th century?



Tuning reduces model bias without violating process fidelity (but poses a problem for validation). From [Golaz et al 2013](#).

# Parameter optimization, elimination, uncertainty quantification

Goal: explore parameter space of model while minimizing the use of expensive forward models.

- **Parametric** uncertainty vs **structural** uncertainty.
- A two stage process: **process fidelity** followed by **global constraints**.
- The choice of **cost function**.
- Metric **weights** and normalization.
- Do observations sample the space sufficiently?
- If models “**higher on the ladder**” are used for calibration, are they representative of all possible states? What are the associated uncertainties?
- Internal feedbacks on **multiple timescales**, and **compensating errors**.

## HighTune: Formulating the problem

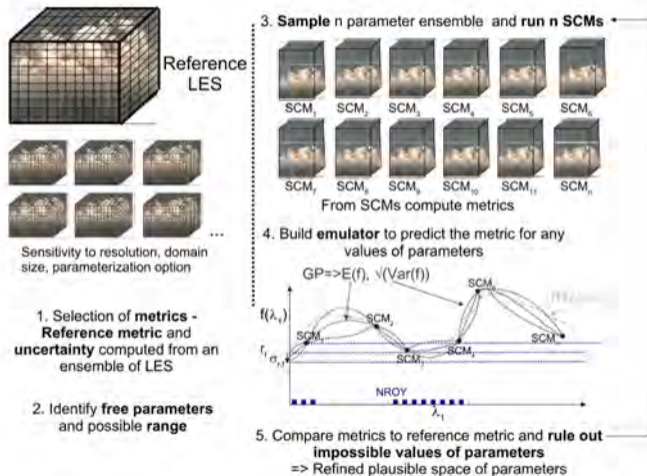
$$\frac{\partial \mathbf{x}}{\partial t} = D(\mathbf{x}) + \sum_n (\mathcal{P}_n(\mathbf{x}, \lambda_n))$$

- Structure is given by  $\mathcal{P}$ , we are trying to calibrate values of a vector of parameters  $\lambda$
- Multiple metrics we wish to satisfy. For each metric  $f$ , define a distance given by:

$$I_f(\lambda) = \frac{\|r_f - E_f[\lambda]\|}{\sigma_{r,f}^2 + \sigma_{d,f}^2 + \text{Var}[f(\lambda)]}$$

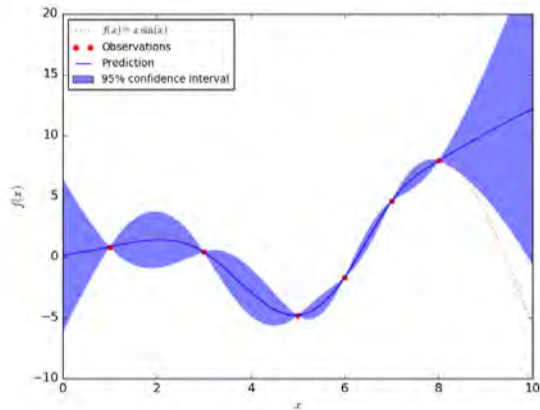
- Euclidean distance over history normalized by error (observational, structural, chaotic)
- Sample  $\lambda$  space as exhaustively as practical for  $I < T$ , the NROY space. Iterate in *waves*. Can use different metrics in subsequent waves.

$$\text{NROY}^n = \cap_k \text{NROY}_{f_k}$$

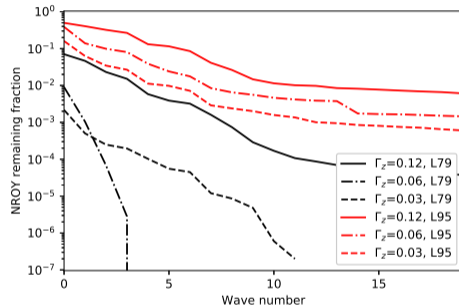
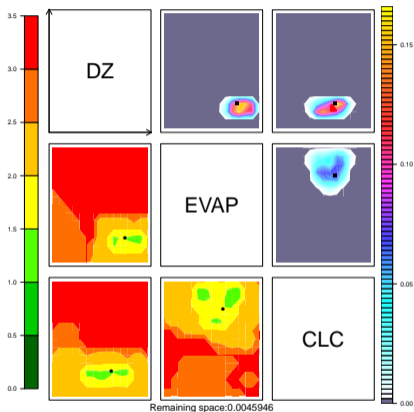


- LES as ground truth, multiple variants to get “observational error”.
- Emulate LES using SCMs encoding all the  $\mathcal{P}$ .
- Latin hypercube sampling of  $\lambda$
- Fit Gaussian processes to SCMs to densely sample all values of  $\lambda$

# Gaussian processes



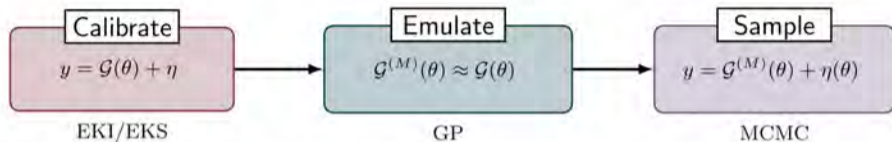
- Extremely standard emulator, widely available in python libraries
- Very poor at extrapolation, so training data must span phase space!



- Eliminate **implausible** parameter space comparing SCMs with LES.
- ... leaving irreducible (“structural”) model error.

- [Couvreur et al 2020](#): Process-based climate model development harnessing machine learning: I. a calibration tool for parameterization improvement.
- [Hourdin et al 2020](#): Process-based climate model development harnessing machine learning: II. model calibration from single column to global
- [Hourdin et al 2017](#): The art and science of climate model tuning.
- [Williamson et al 2013](#): History matching for exploring and reducing climate model parameter space using observations and a large perturbed physics ensemble
- [Williamson et al 2017](#): Tuning without over-tuning: parametric uncertainty quantification for the NEMO ocean model

# CLiMA: Calibrate, Emulate, Sample



**Fig. 1.** Schematic of approximate Bayesian inversion method to find  $\theta$  from  $y$ . EKI/EKS produce a small number of approximate (expensive) samples  $\{\theta^{(m)}\}_{m=1}^M$ . These are used to train a GP approximation  $\mathcal{G}^{(M)}$  of  $\mathcal{G}$ , used within MCMC to produce a large number of approximate (cheap) samples  $\{\theta^{(n)}\}_{n=1}^{N_s}$ .  $N_s \gg M$ .

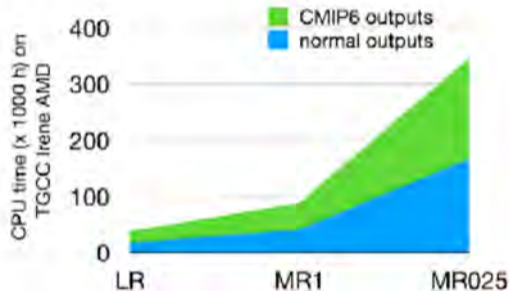
- *Calibrate*: approximately locate attractor using **expensive** forward model
- *Emulate*: **cheap** GP emulator to map parameter space near attractor
- *Sample*: MCMC sampling of parameter space for **uncertainty quantification** (parameter vector with error bounds)

Applied to boundary layer and shallow cloud (EDMF) parameterizations, [Cleary et al 2020](#), [Dunbar et al 2021](#).



- [Schneider et al \(2017\)](#): Earth System Modeling 2.0: A Blueprint for Models That Learn From Observations and Targeted High-Resolution Simulations
- [Pressel et al 2017](#): Numerics and subgrid-scale modeling in large eddy simulations of stratocumulus clouds
- [Cleary et al 2020](#): Calibrate, emulate, sample
- [Dunbar et al 2021](#); Calibration and Uncertainty Quantification of Convective Parameters in an Idealized GCM
- [Shen et al 2021](#): A Library of Large-eddy Simulations for Calibrating Cloud Parameterizations

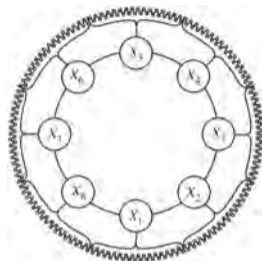
# Beyond LES: calibration of coupled models



Post Hourdin et al automatic tuning:

- 5 new piCtrl coupled simulations, 250 SY each
  - excessive cold biases and sea ice cover relative to baseline IPSL-CM6
  - required extensive retuning of ocean and sea ice!
- 
- GFDL experience is similar: about 50000 SY of coupled runs of CM4 and ESM4 during model calibration in addition to AMIP.

# Lorenz 96, a nice abstraction

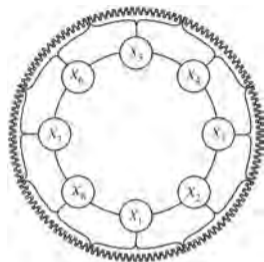


$$\frac{dX_k}{dt} = -X_{k-1}(X_{k-2} - X_{k+1}) - X_k + F - \frac{hc}{b} \sum_{j=1}^J Y_{j,k} + f \quad (1)$$

$$\frac{dY_{j,k}}{dt} = -cbY_{j+1,l}(Y_{j+2,k} - Y_{j-1,k}) - cY_{j,k} + \frac{hc}{b} X_k \quad (2)$$

- A simplified multiscale system ( $X$  and  $Y$  can stand for **resolved/unresolved**, **slow/fast**), where coupling strength can be varied... maybe **too interesting**? See metastability issues in [Schneider et al \(2017\)](#).
- Maybe **too simple**? (from Stephan Rasp's blog)

# Lorenz 96 again: history matching for an “AOGCM”

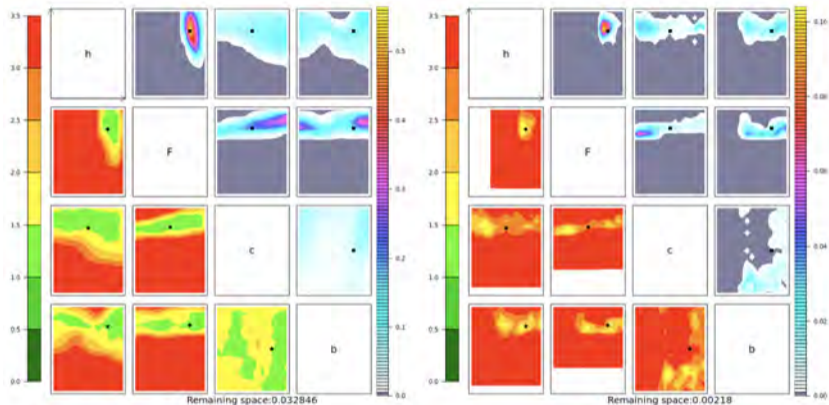


$$\frac{dX_k}{dt} = -X_{k-1}(X_{k-2} - X_{k+1}) - X_k + F - \frac{hc}{b} \sum_{j=1}^J Y_{j,k} + f \quad (1)$$

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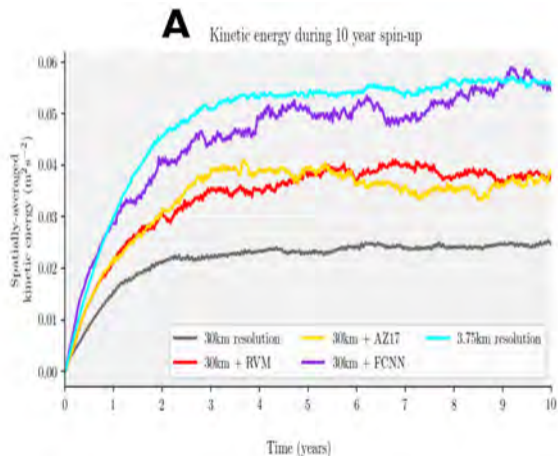
- Similar metrics to [Schneider et al \(2017\)](#)  $f(X, Y) = (X, \bar{Y}, X^2, X\bar{Y}, \bar{Y}^2)$
- as usual try to recover  $F, h, \log c, b$  from prior “truth” run.
- AMIP: apply only  $Y$  constraints; OMIP = apply only  $X$  constraints.
- Investigate length of sample needed for training.
- Lguensat, Balaji, Deshayes 2021, *in prep.*

# History Matching on Lorenz96



- History matching efficiently reduces NROY space.
- “AMIP” and “OMIP” experiments underway.
- From Lguensat, Balaji, Deshayes, *in prep*.

# Discovering subgrid momentum closures

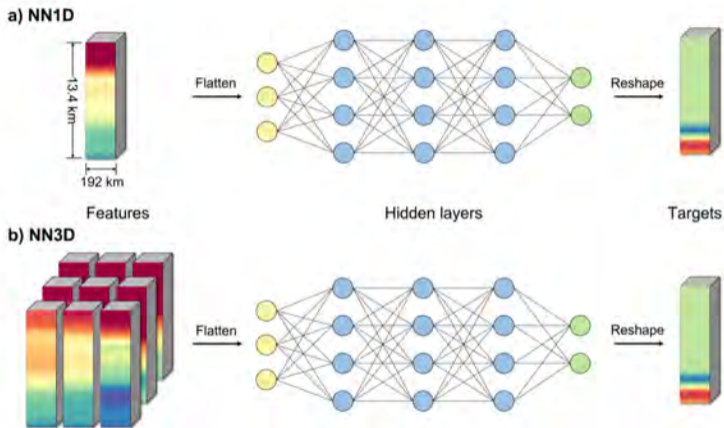


Zanna and Bolton 2020 returns a closed-form expression for subgrid momentum closures:

$$\mathbf{S}_u = (\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} - \overline{\mathbf{u} \cdot \nabla \mathbf{u}}$$

where *relevance vector machine* techniques yield a representation similar in form to Anstey and Zanna (2017).

# Non-local parameterizations using ML



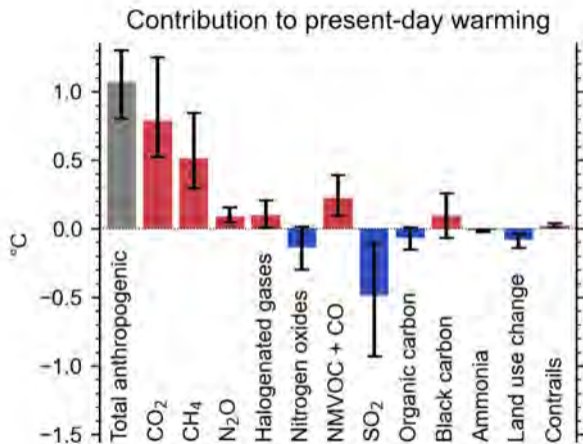
From [Wang et al \(2021\)](#). Can be non-local in (past) time as well! The DataWave project is attempting similar approaches for gravity wave parameterization.

# Bibliography

- Schmidt and Lipson, *Science*, 2009: Distilling Free-Form Natural Laws from Experimental Data.
- Gaitán, Balaji and Moore (2016): *Can we obtain viable alternatives to Manning's equation using genetic programming?*
- Rudy et al (2017): Data-driven discovery of partial differential equations
- Zanna and Bolton 2020: Data-driven Equation Discovery of Ocean Mesoscale Closures
- Balaji 2021: Climbing down Charney's ladder: machine learning and the post-Dennard era of computational climate science

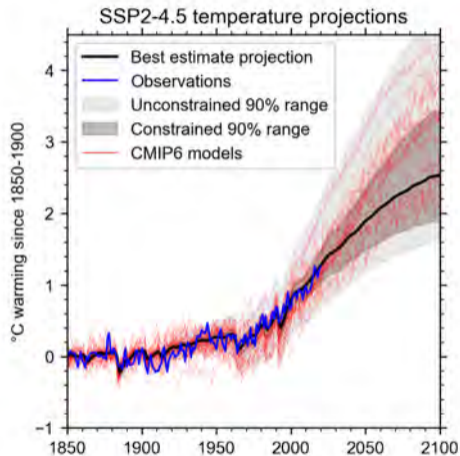


# Emulators in IPCC-AR6: sampling counterfactuals



From Chris Smith's [CarbonBrief](#) guest post, 28 Sep 2021.

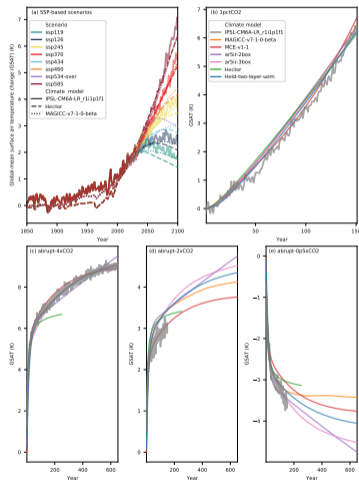
# Emulators in IPCC-AR6: reducing CMIP6 spread in ECS



From Chris Smith's [CarbonBrief](#) guest post, 28 Sep 2021.

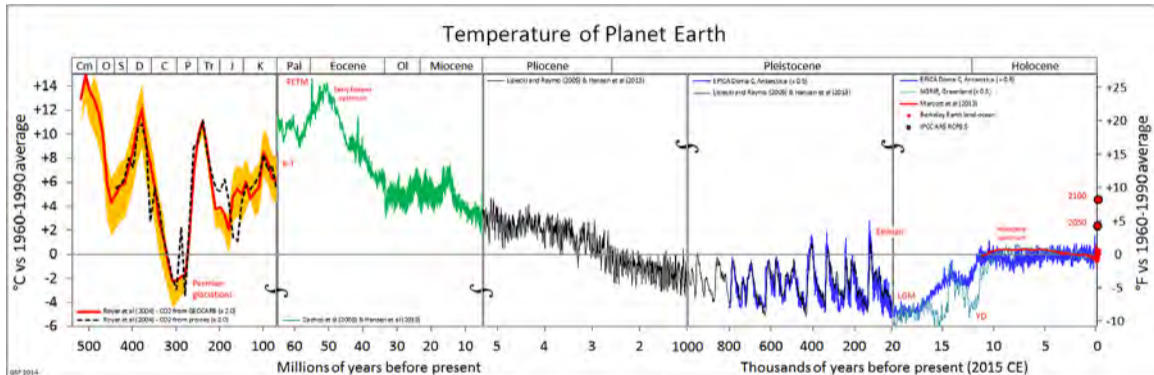
# Structural uncertainty across reduced complexity models

- RCMs vary a lot in design: impulse-response models, single column models of varying complexity
- Millions of times faster than ESMs!
- Connection to climate physics can be tenuous!
- “The role of the ESM is increasingly as a target for robust emulation”: [Ben Sanderson, WGCM24, Dec 2021](#).



From [Nicholls et al \(2020\)](#).

# Paleoclimate constraints on sensitivity



- From [Wikipedia](#).
- Paleoclimate provides stringent out-of-sample tests on novel climate models, and a strong separate line of evidence on ECS, see [Sherwood et al \(2020\)](#).

# Past warm climates

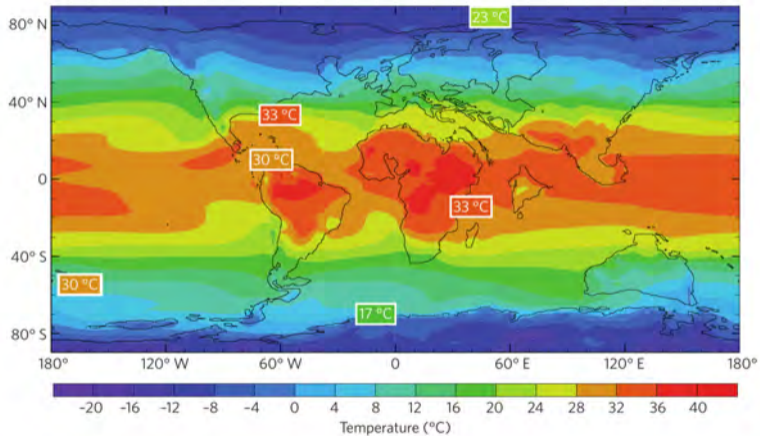


Fig 1 from [Valdes \(2011\)](#).

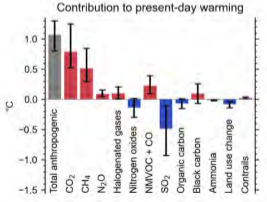
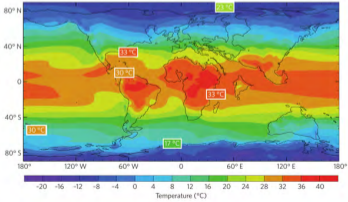
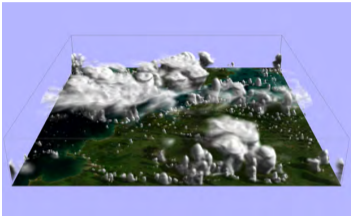
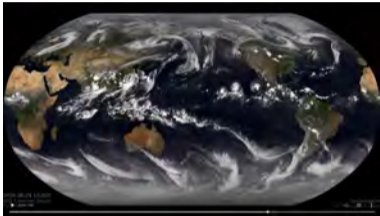
# Outline

- 1 The structure of the GCM, from Manabe to present-day
- 2 Computing technology: bigger, not faster
- 3 Emulators: climbing down the ladder
- 4 Are GCMs obsolete?

# Some remarks

- **Climate is not weather**: in the ML era, they might further diverge, as **model-free methods** become successful in weather forecasting. See Guardian, 9 January 2022: [Are we witnessing the dawn of post-theory science?](#)
- **Computers are getting bigger, not faster**: which is ok for **weak scaling** problems (more degrees of freedom, same SYPD), but not for **strong scaling** (fewer degrees of freedom, more SYPD).
- **There is always a cost function**: any model has been calibrated to meet its requirements (“**fit for purpose**”). Can new methods yield model development in **weeks, not years**?
- **Model calibration is needed at any resolution**: we need methods of fast sampling of parametric and structural uncertainty.
- **Decoupling** of reduced-complexity models from climate models carries **epistemic risk**.
- Readings: [Charney's ladder](#), [Are GCMs obsolete?](#) (submitted to PNAS), Saravanan's book [The Climate Demon](#), [Ben Sanderson's excellent talk at WGCM24](#).
- Workshops: [Modeling Hierarchies 2022](#).

# GCMS, not the end of the road, but the crossroads!





# Extract from Manabe press conference, 5 October 2021



on [Youtube](#). Other links: [Annonce CEA](#), [La Météorologie](#)